

## Grid Example: Rotor Angle Stability with HVDC Light Link

The following pages shows how the rotor angle stability of a small network connected through an ABB HVDC Light link. Three different control strategies for the HVDC-link are implemented in this small NEPLAN example.

The small ABB HVDC Light model may be found at the ABB site:

<http://www.abb.com/cawp/GAD02181/C1256D71001E0037C1256D2600278534.aspx>

It shows the also the efficiency of the NEPLAN Dynamic Simulator and how fast an easy user defined models may be developed.

See:

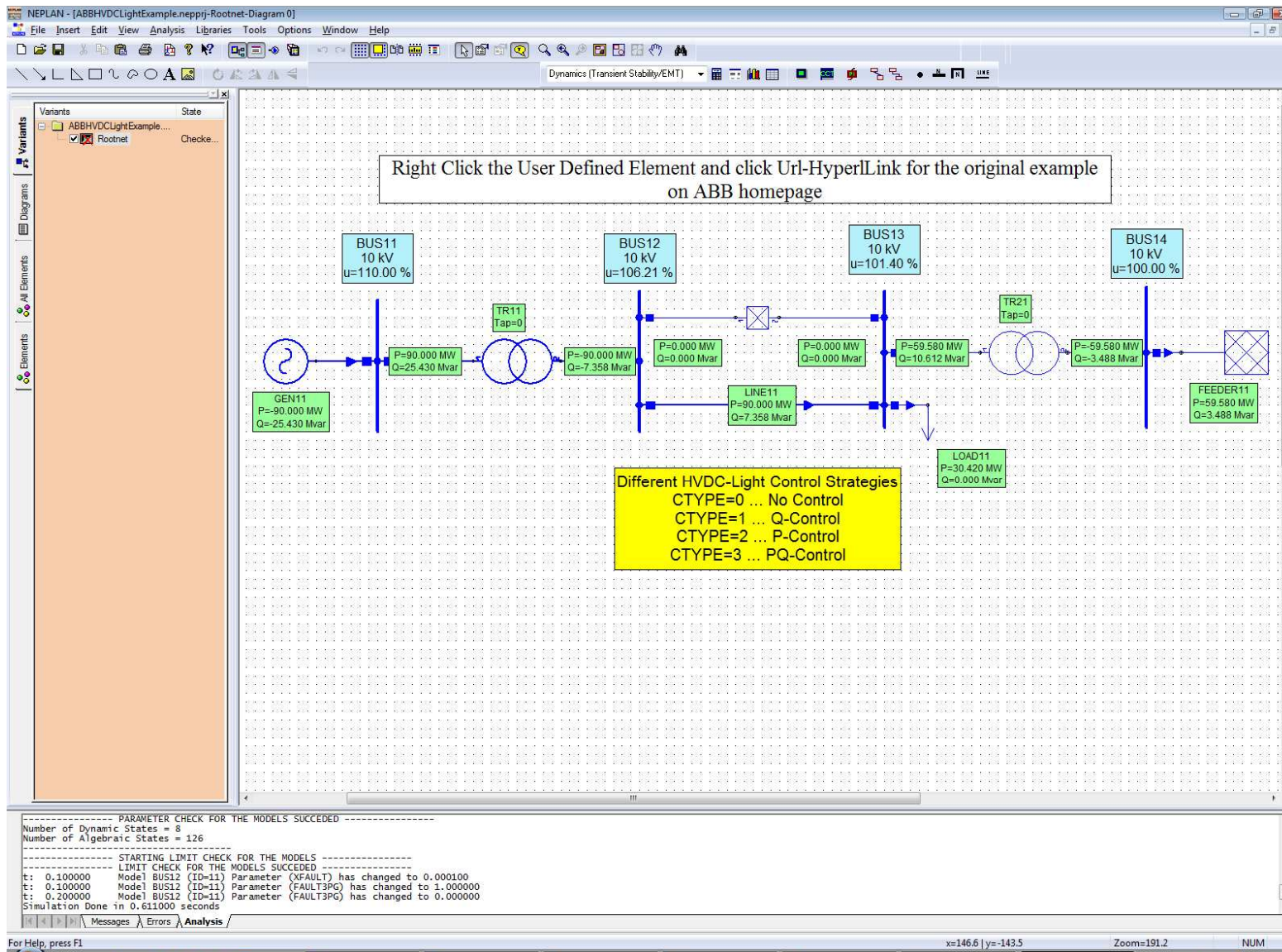
[www.neplan.ch](http://www.neplan.ch)

[http://www.neplan.ch/pdf/english/modules/NEPLAN\\_B08\\_Simulator\\_engl.pdf](http://www.neplan.ch/pdf/english/modules/NEPLAN_B08_Simulator_engl.pdf)

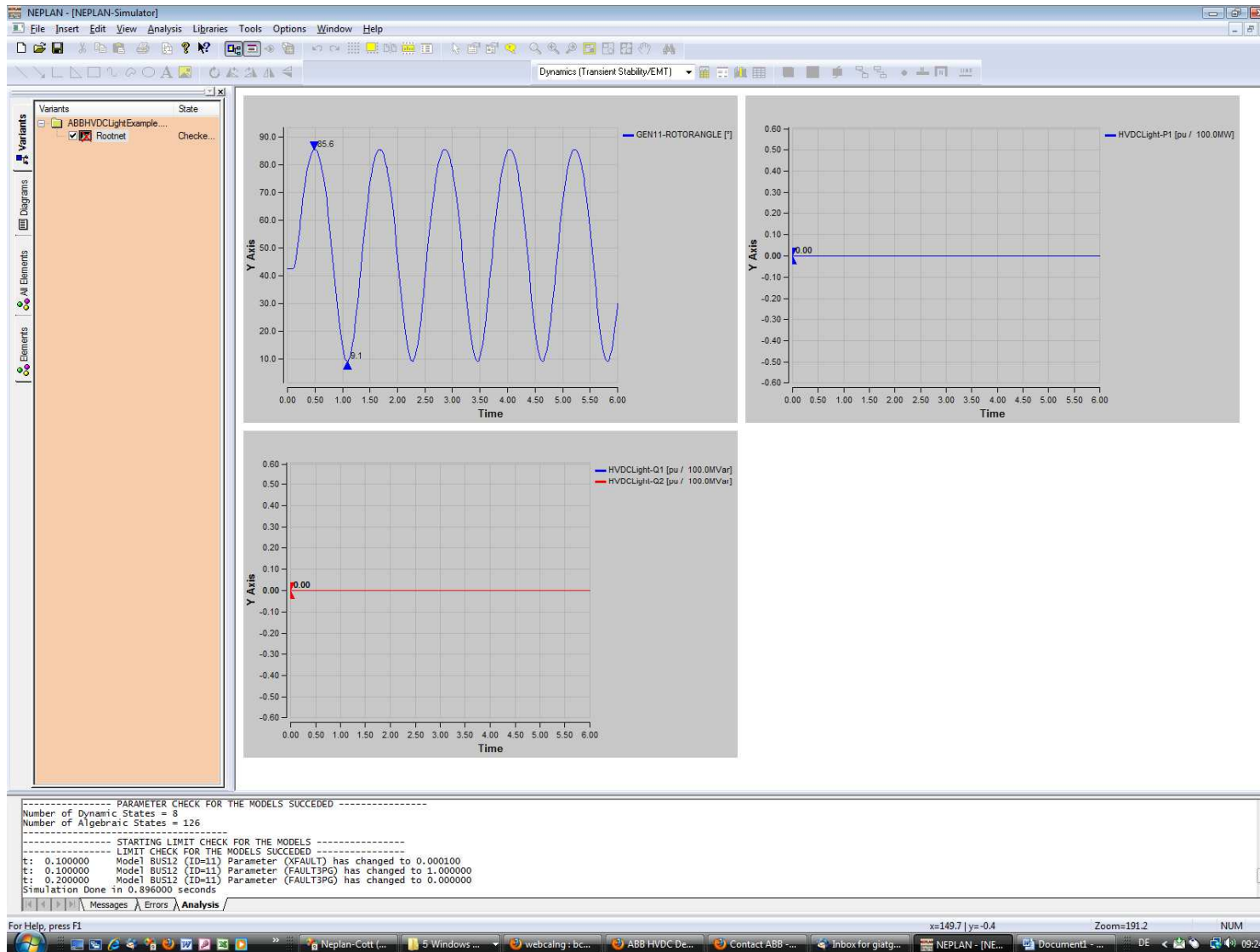
This is a standard example in NEPLAN, which will be available in Version 5.4.2. It may be changed and adapted also in the demo version and might be shown to potential HVDC clients.

The NEPLAN Demo may be downloaded at:

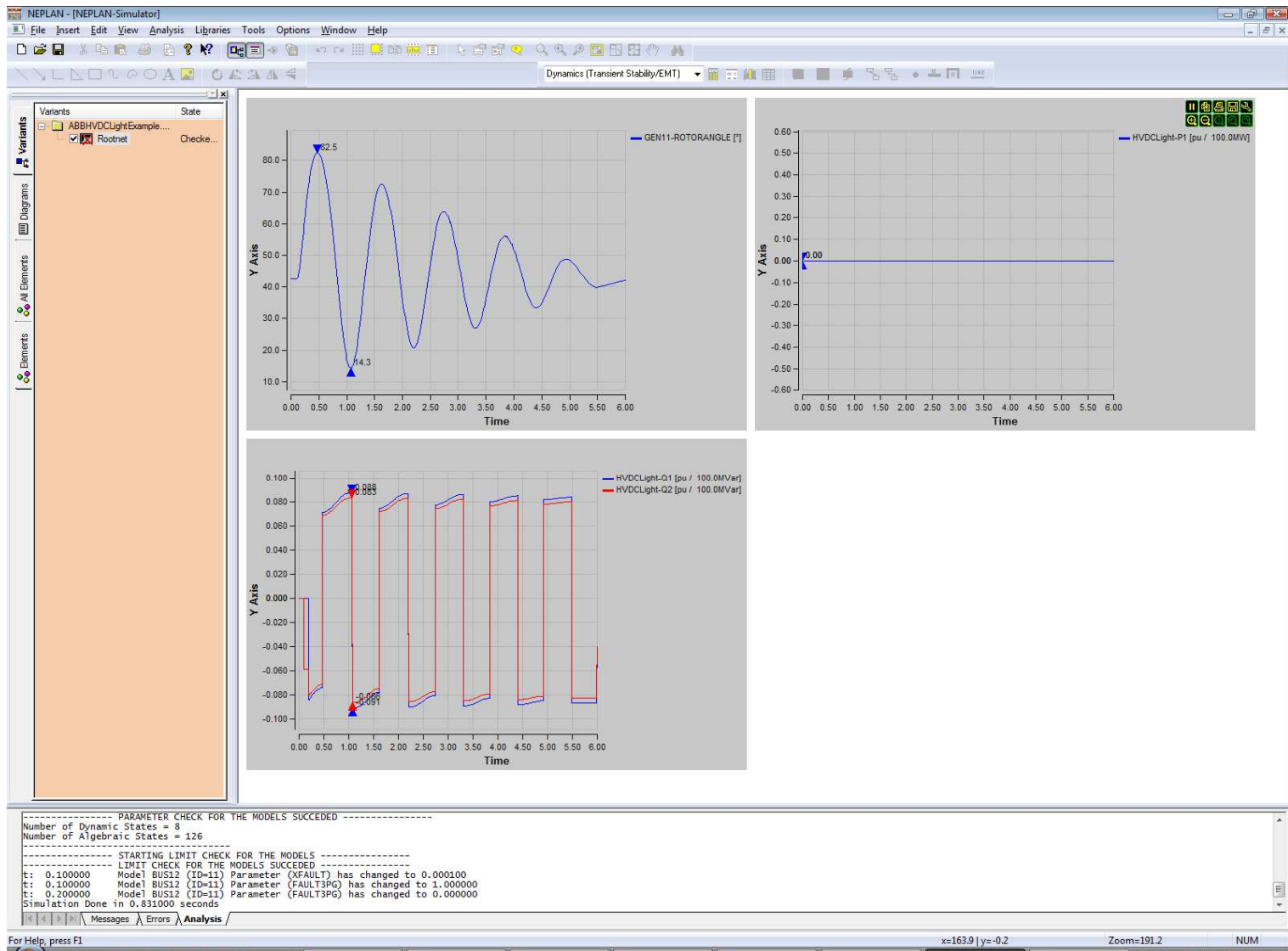
[http://www.neplan.ch/support\\_area/index.php?action=REQUEST&interest=Demo](http://www.neplan.ch/support_area/index.php?action=REQUEST&interest=Demo)



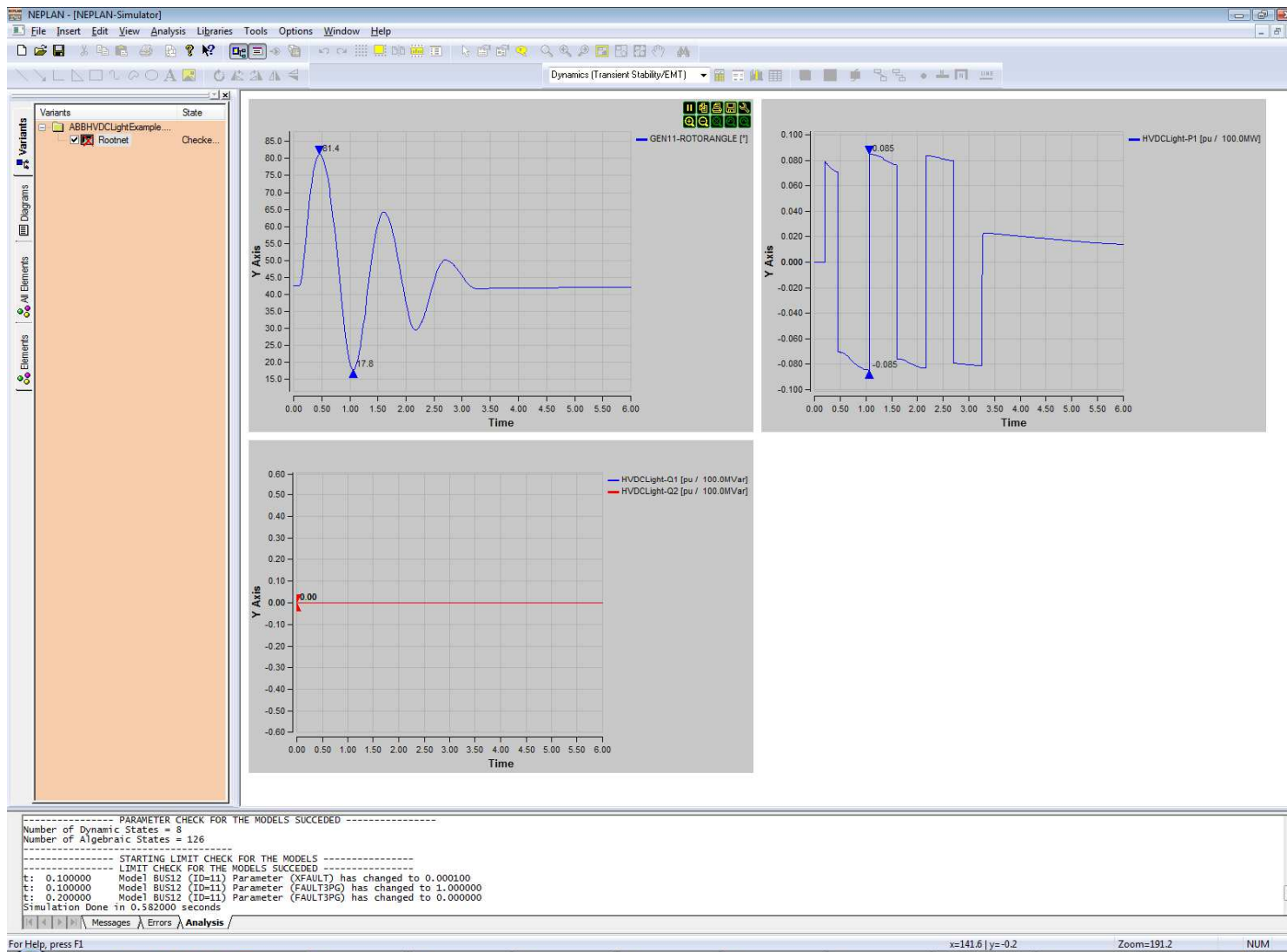
**NEPLAN Network with a user defined model of the HVDC Link**



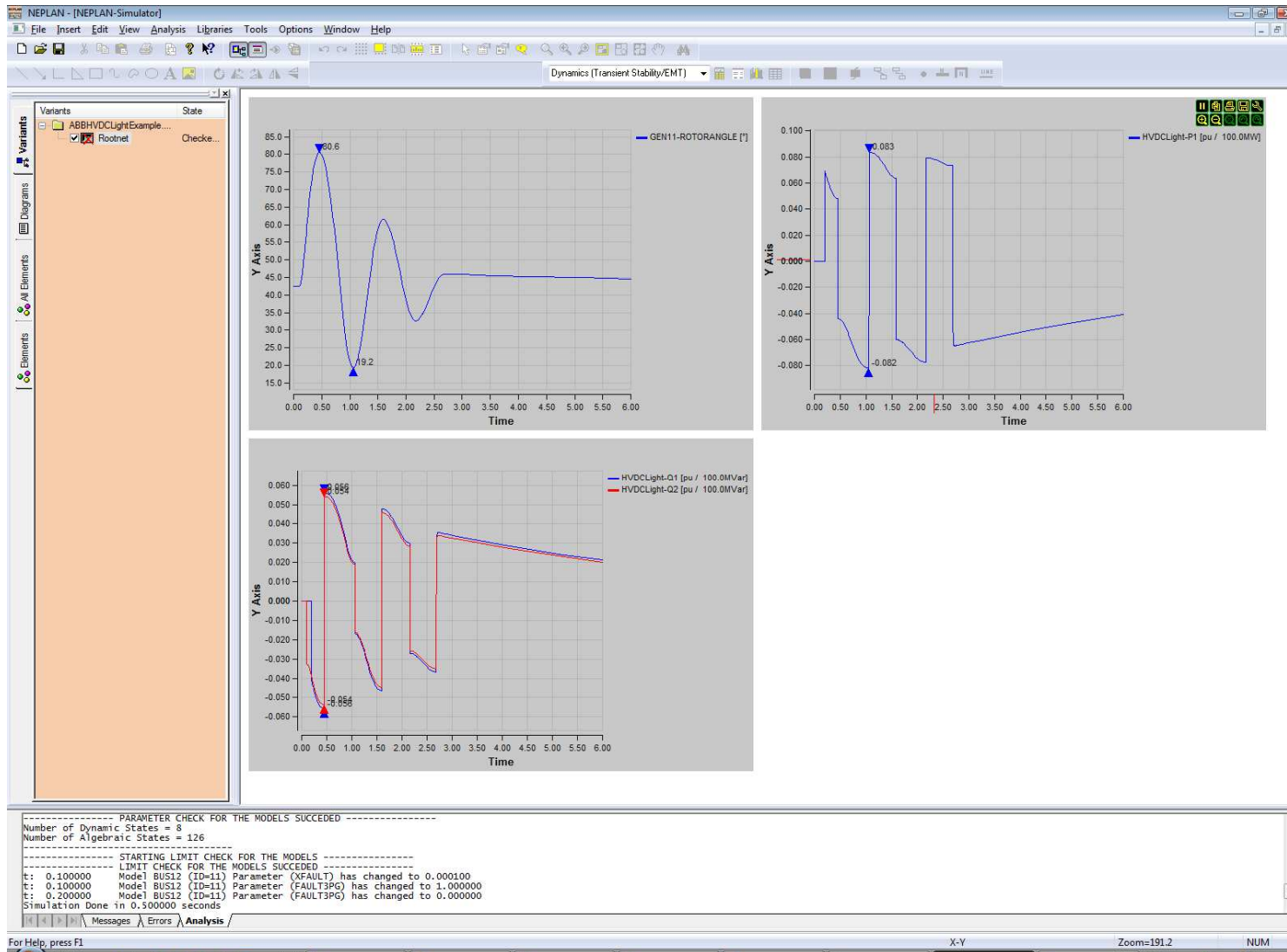
## Results of the simulation with NO Control



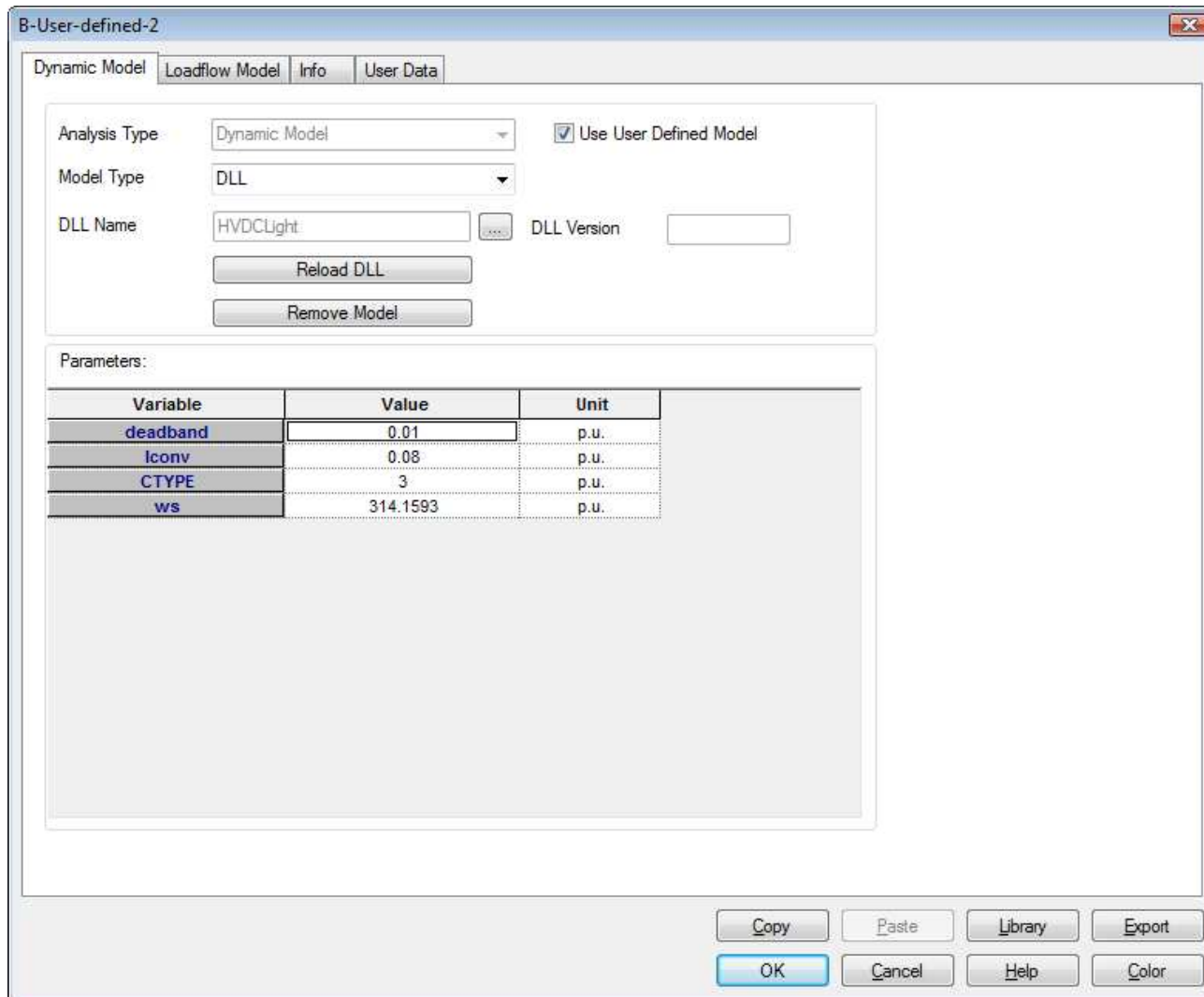
## Results of the simulation with Q Control



## Results of the simulation with P Control



## Results of the simulation with PQ Control



**Dialog of the User Defined HVDC Light model.**

**The model is hidden in a binary DLL file. The user does not see the implementation of the model**

**The user may only change the input parameters.**

**Below is the HVDC Light Model defined in a symdef file. This file will be compiled from Matlab to a DLL**

```
%-----
definitions:
%-----
inputs VD1=1 VQ1 VD2=1 VQ2 W
external_states ID1 IQ1 ID2 IQ2 P1 P2 Q1 Q2
internal_states VMAG1=1 VMAG2=1 VMIN COSDELTA=1 SINDELTA
events !ev_W1 !ev_W2
parameters Iconv=0.08 deadband=0.01 ws=3.141592653589793e+002 CTYPE
%-----
initializations:
%-----

%-----
f_equations:
%-----

%-----
g_equations:
%-----
g01 = P1 - (VD1*ID1 + VQ1*IQ1)
g02 = Q1 - (VQ1*ID1 - VD1*IQ1)
g03 = P2 - (VD2*ID2 + VQ2*IQ2)
g04 = Q2 - (VQ2*ID2 - VD2*IQ2)
g05 = P1 + P2
g09 = VMAG1 - magnitude(VD1,VQ1,1.0)
g10 = VMAG2 - magnitude(VD2,VQ2,1.0)
g11 = VMIN - min(VMAG1,VMAG2)
g12 = ev_W1 - (W - ( 1.0 + deadband/ws ))
g13 = ev_W2 - (W - ( 1.0 - deadband/ws ))
if t < 0
    g06 = P1
    g07 = Q1
    g08 = Q2
else
    if CTYPE == 0
```



```

g06 = P1
g07 = Q1
g08 = Q2
else
  if CTYPE == 1
    if ev_W1 > 0
      g06 = P1
      g07 = Q1 + VMAG1*Iconv
      g08 = Q2 + VMAG2*Iconv
    else
      if ev_W2 < 0
        g06 = P1
        g07 = Q1 - VMAG1*Iconv
        g08 = Q2 - VMAG2*Iconv
      else
        g06 = P1
        g07 = Q1 + VMAG1*Iconv*ws*(W-1.0)/(deadband)
        g08 = Q2 + VMAG2*Iconv*ws*(W-1.0)/(deadband)
      end
    end
  end
  else
    if CTYPE == 2
      if ev_W1 > 0
        g06 = P1 - Iconv*VMIN
        g07 = Q1
        g08 = Q2
      else
        if ev_W2 < 0
          g06 = P1 + Iconv*VMIN
          g07 = Q1
          g08 = Q2
        else
          g06 = P1 - VMIN*Iconv*ws*(W-1.0)/deadband
          g07 = Q1
          g08 = Q2
        end
      end
    end
  end
  else
    if CTYPE == 3

```

```

if ev_W1 > 0
    g06 = P1 - COSDELTA*Iconv*VMIN
    g07 = Q1 + SINDELTA*VMAG1*Iconv
    g08 = Q2 + SINDELTA*VMAG2*Iconv
else
    if ev_W2 < 0
        g06 = P1 + COSDELTA*Iconv*VMIN
        g07 = Q1 - SINDELTA*VMAG1*Iconv
        g08 = Q2 - SINDELTA*VMAG2*Iconv
    else
        g06 = P1 - COSDELTA*VMIN*Iconv*ws*(W-1.0)/deadband
        g07 = Q1 + SINDELTA*VMAG1*Iconv*ws*(W-1.0)/deadband
        g08 = Q2 + SINDELTA*VMAG2*Iconv*ws*(W-1.0)/deadband
    end
end
end
end
end
end
end
end
end
g21 = COSDELTA - ((VD1/VMAG1)*(VD2/VMAG2)+(VQ1/VMAG1)*(VQ2/VMAG2))
g22 = SINDELTA - ((VQ1/VMAG1)*(VD2/VMAG2)-(VD1/VMAG1)*(VQ2/VMAG2))
%-----
h_equations:
%-----

%-----
measurements:
%-----

%-----
checkparameters:
%-----

```